High-Dimensional Bayesian Optimization with Multi-Task Learning for RocksDB

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과제명: loT 환경을 위한 고성능 플래시 메모리 스토리지 기반 인메모리 분산 DBMS 연구개발

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#### Abstract

Maximizing the throughput of RocksDB IO operations by auto-tuning then parameters of var ying ranges

#### **High-Dimensional Problem**

- multi-task modeling
- dimensionality reduction through clustering

#### Introduction

Auto-tuning method 필요한 이유

A high-dimensional optimization space is a common phenomenon in general-purpose systems as they have many **parameters** and **objectives** 



#### Introduction

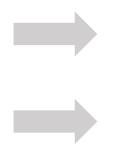
#### **Bayesian Optimization(BO)**

- A sample efficent tuner, has received considerable attention in recent years due to its versatility and efficiency
- The framework, first builds a system model and then uses the model to find an optimal configuraiton

### Introduction

BO's drawback is its inability to handle heigh-dimensional spaces

- Curse of dimensionality
- A computationally expensive operation in the surrogate model



Optimizing over **multiple targets** to increase learning mileage per training sample

Decomposes into a subset of system components that influence the primary target.

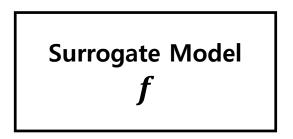
# Background

- RocksDB is a key-value store based on LevelDB that provides efficient concurrent reads and writes
- RocksDB stores new data in a Log-Structured Merge-Tree(LSM-Tree) format in memory
  - Once the memtable is full, RocksDB flushes it sequentially into a Sorted Sequenc e Tree(SST) file on disk
  - Rocks DB still processes concurrent writes during the flushing process
- SST organizes the data in levels starting from level-0 to level-n
  - When a level is full, it performs a housekeeping operaion(compaction) that merges and re moves tombstones
  - During compaction, RocksDB stalls new writes, leading to a reduced IO throughput and inc reased latency

Background

#### **Bayesian Optimization**

BO is a sample efficient optimization framework that solves the problem of **block-box functio n** optimization

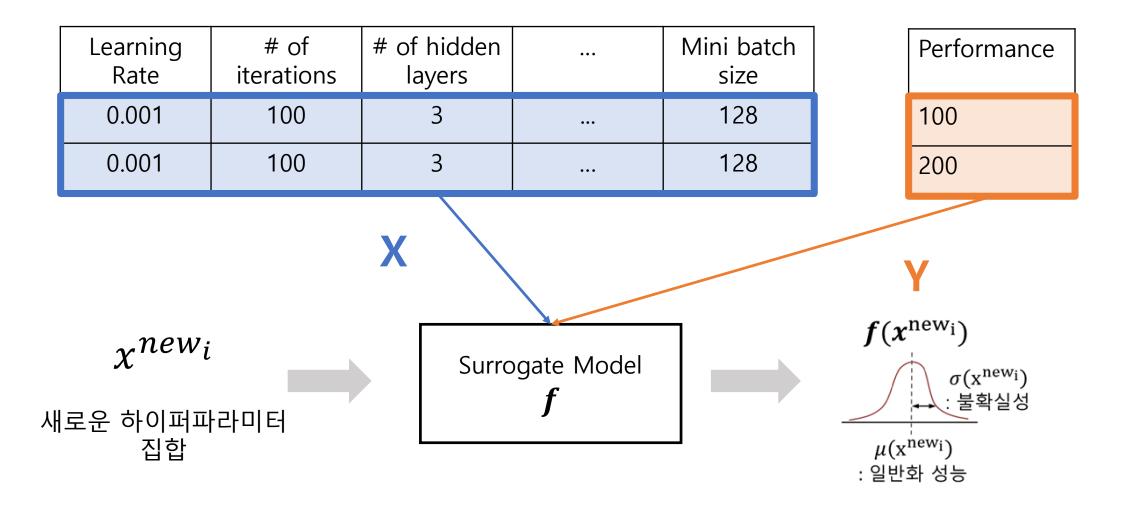


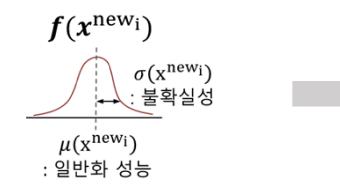
• contains a belief of the system and updates at every now observation

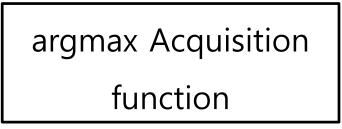
argmax Acquisition function

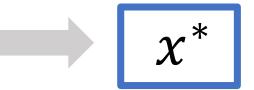
• performs numerical optimization operations over the model to find configurations to test next on the objective function

# Background



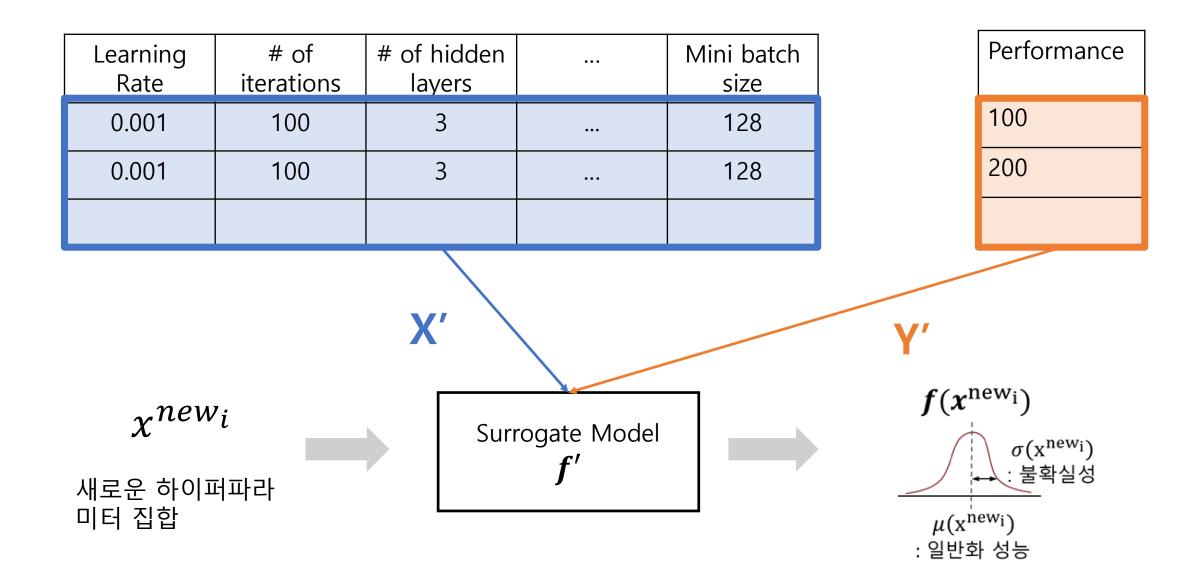






Learning Rate	# of iterations	# of hidden layers	 Mini batch size
0.001	100	3	 128
0.001	100	3	 128
		<b>X</b> *	

Performance
100
200



## Structured multi-task optimization

#### overveiw

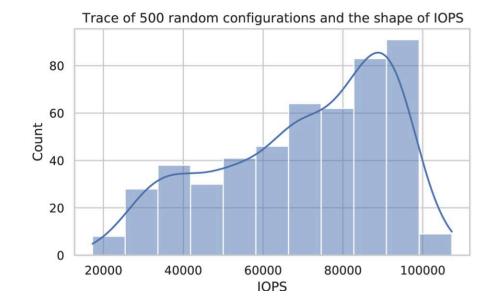
- Used multi-task learning to capture the intersection between system components
- Learn more from every sample, reducing the observation needed for convergence
- Reduces the dimensions through a manual grouping of parameters to speed up the convergence

### Problem space and assumptions

The fundamental assumption in using GP

- the function is differentiable at every point
- the modeling space is a multivariate Gaussian distribution

We performed **500 independent experime nts** where we randomly sampled the model ing space(then parameters)



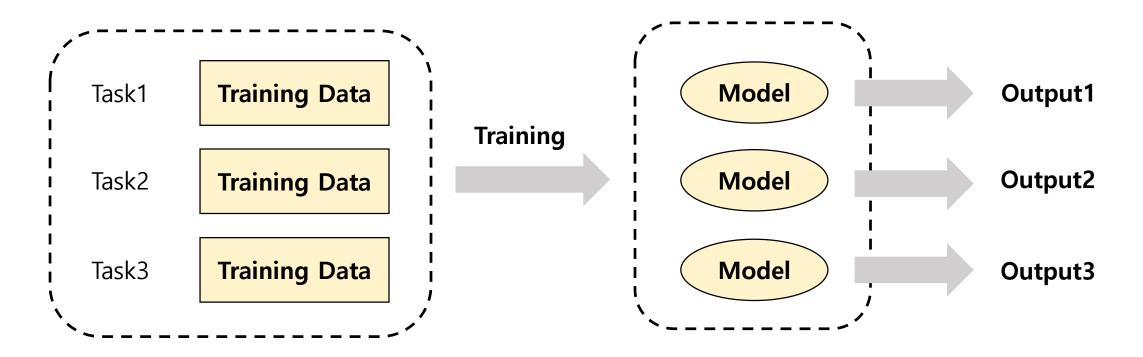
# Multi-task learning

Chose three additional objectives based on our understanding of Rocks DB architecture

- WriteAmplification : the ratio of bytes written to storage to the bytes written to the backend.
- **ReadBlockGetP99** : The 99<sup>th</sup> percentile latency to read a block of data.
- Level0Tolevel1P99 : The 99<sup>th</sup> percentile time it takes to compact blocks stored in level0 to level1.

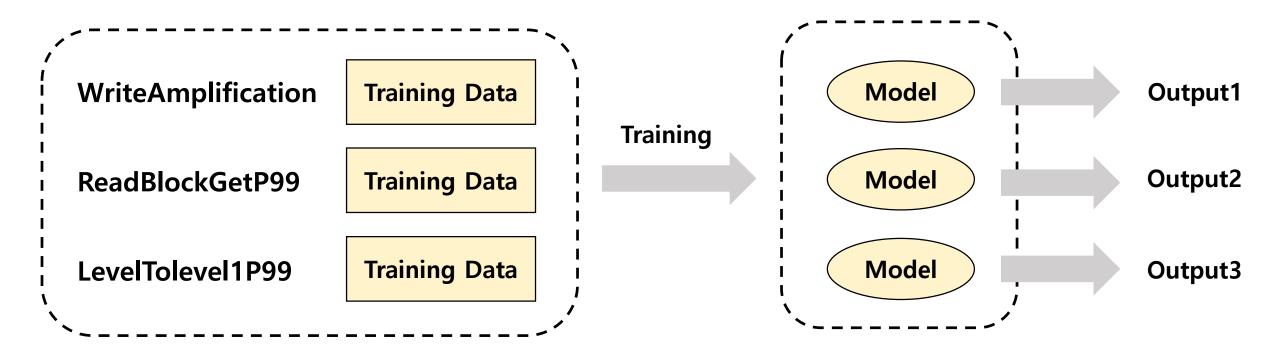
# Multi-task learning

A machine learning method based on shared representations, which uses task multit asking for learning



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# Multi-Task learning in GP

Intrinsic Coregionalization Model (ICM kernel)

 $k_{x}(x, x')$ 

 $k_T(m,m')$ 

$$k((x,m),(x',m')) = k_x(x,x')k_T(m,m')$$

The parameter covariance kernel

The task similarity kernel

# ICM challenges

- ICM method provides a neat trick to get more mileage out of the few sample
- A standard GP inference is  $O(Tn^3)$ , duplicating the data to the number of tasks scales this to

#### Curse of dimensionality 문제 해결되지 않음!!

# Decomposability through clustering

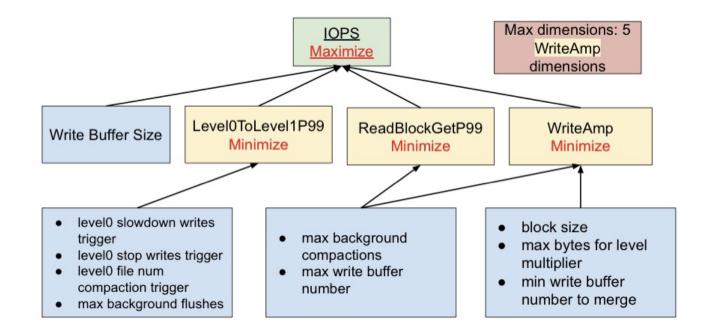
The decomposability refers to the smallest unit of obseravable RocksDB's performace metric and a corre sponding set of parameters in this context



Using the 500 random configurations thrace, we calculated **the correlations betw een IOPS and the 517 observable metric** from RocksDB and **the correlations be tween them to the parameters** 



# Decomposability through clustering





각 architecture와 관련있는 cluster와 parameter들을 입력값으로 Bayesian Optimization 진행

# Decomposability through clustering

**Table 1.** RocksDB parameters and their impact. All reportedparameters are discrete ordinal variables.

Parameter	Range	Default
max_background_compactions	$[1, 2^8]$	1
max_background_flushes	[110]	1
write_buffer_size	$[1, 15 * 10^7]$	$2^{26}$
max_write_buffer_number	$[1, 2^7]$	2
min_write_buffer_number_to_merge	$[1, 2^5]$	1
max_bytes_for_level_multiplier	[5, 15]	10
block_size	$[1, 5 * 10^5]$	$2^{12}$
level0_file_num_compaction_trigger	$[1, 2^8]$	$2^{2}$
level0_slowdown_writes_trigger	$[1, 2^{10}]$	0
level0_stop_writes_trigger	$[1, 2^{10}]$	36

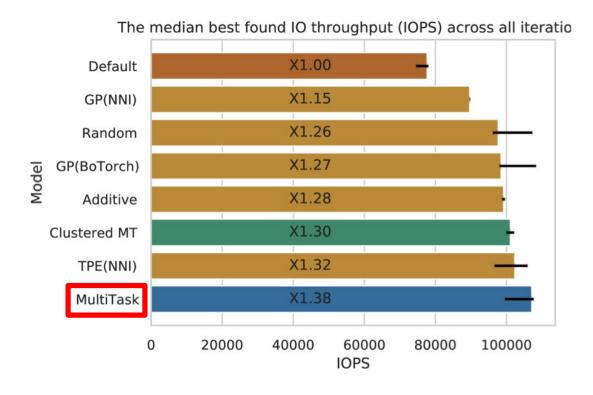
#### Evaluation

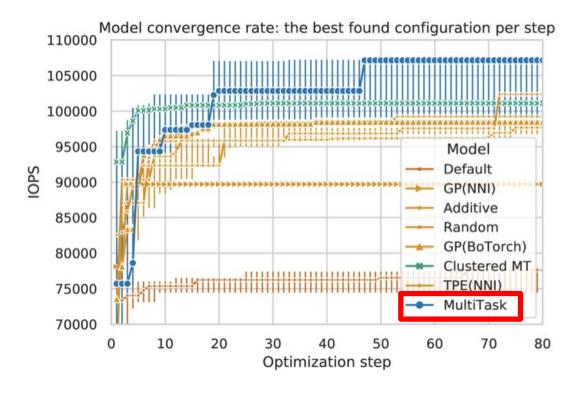
- used RocksDB's benchmark tool **db\_bench**
- Set a budget of 100 optimization steps

**Table 2.** Alternative surrogate models as baselines. The background has a short introduction to these methods 2.3.

Method	Use case	
TPE [4]	Handles discrete parameters.	
GP (NNI) [29]	Standard $O(n^3)$ implementation.	
Random [5]	Low effective search dimensions.	
Additive kernel [15]	Low-dimensions decomposability.	
Default	RocksDB v6.17 default settings.	
BoTorch [3]	Efficient GPyTorch $O(n^2)$ GP.	

#### Evaluation





IO Troughput이 가장 높다

가장 빠르게 증가한다

### Conclusion

- The tuner exploits alternative observable metrics and structural decomposability to converge f aster and reduce the dimensional space
- Utilize multi-task learning to provide an accessible mechanism for expressing structure in the model
- Tuner outperformed the default configuration by x1.35 in 10 iterations, compared to the other state-of-the-art methods requiring 60 iterations